

Fall 2021 ME424 Modern Control and Estimation

Linear Algebra Review: Part III
Geometry ~ linear algebra

Prof. Wei Zhang
Department of Mechanical and Energy Engineering
SUSTech Institute of Robotics
Southern University of Science and Technology

zhangw3@sustech.edu.cn
<https://www.wzhanglab.site/>

Outline

- Inner product
- Projection
- Geometric sets
 - Lines
 - Convex set and cone
 - Hyperplanes
 - Polytopes
 - Ball, ellipsoid

Inner Product

- Inner product of vectors in R^n : $\langle v, w \rangle \stackrel{\Delta}{=} v_1 w_1 + v_2 w_2 + \dots + v_n w_n$

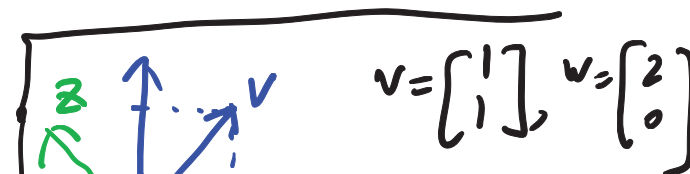
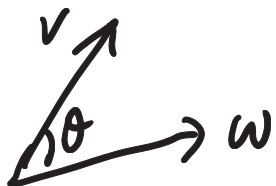
$$\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}, \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$$

$$= \sum_{i=1}^n v_i w_i = v^T w$$

- Norm of $v \in R^n$: $\|v\| = \sqrt{\langle v, v \rangle} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$

- Angle between $v, w \in R^n$:

$$\cos \theta = \frac{\langle v, w \rangle}{\|v\| \|w\|}$$



$$\cos \theta = \frac{\langle v, w \rangle}{\|v\| \|w\|} = \frac{2}{\sqrt{2} \cdot 2} = \frac{\sqrt{2}}{2}$$

$$z = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$v^T z = 0$$

- Orthogonality:

$$v \perp w \Rightarrow \cos \theta = 0 \Rightarrow \langle v, w \rangle = v^T w = 0$$

Inner Product

- General inner product $\langle \cdot, \cdot \rangle: V \times V \rightarrow R$
- maps each pair in a vector space to a scalar
- satisfies several key properties: linearity, conjugate, positive definiteness ...

$$f = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix} \quad g = \begin{bmatrix} g_1 \\ \vdots \\ g_n \end{bmatrix}$$

vector space for which inner product can be defined is called inner product space

- Inner product of matrices in $R^{m \times n}$: $\langle A, B \rangle \triangleq \text{tr}(A^T B) = \text{tr}(A B^T)$

eg: $A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \\ 0 & -1 \end{bmatrix}, B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

$m \times n$ matrices

$\text{tr}(\cdot) = \text{sum of diagonals}$
 $= \sum_{i=1}^m \sum_{j=1}^n A_{ij} B_{ij}$

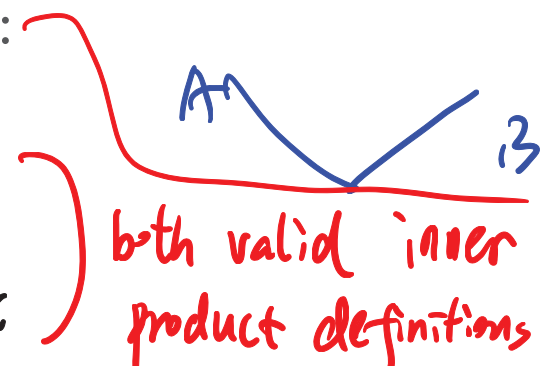
$$\langle A, B \rangle = \text{tr}(A^T B) = \text{tr} \left(\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = \text{tr} \left(\begin{bmatrix} 0 & 1 \\ 1 & -2 \end{bmatrix} \right) = -2, \quad \langle (A, B) \rangle = 9$$

- Inner product of two functions f, g on interval $[a, b]$:

$$\begin{cases} f: [a, b] \rightarrow \mathbb{R} \\ g: [a, b] \rightarrow \mathbb{R} \end{cases}$$

$$\langle f, g \rangle \triangleq \int_a^b f(x)g(x)dx$$

or $\triangleq \frac{1}{|b-a|} \int_a^b f(x)g(x)dx$
 another choice

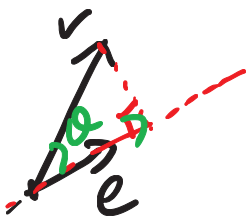


both valid inner product definitions

however, yields different geometry.

Projection

- Projection of $v \in R^n$ along direction e :



suppose $\|e\|=1$, unit vector

If $\|e\| \neq 1$, we can normalize it

$$\text{Proj}_e(v) = (\|v\| \cos \theta) \cdot e$$

$$\text{Proj}_e(v) = \langle v, \frac{e}{\|e\|} \rangle \cdot \frac{e}{\|e\|}$$

$$= \frac{\|v\| \langle v, e \rangle}{\|v\| \cdot 1} \cdot e$$

$$= \langle v, e \rangle \cdot e$$

- $\{e_1, \dots, e_k\}$ be orthonormal basis of vector space V , then any $v \in V$,

$$v = \langle v, e_1 \rangle e_1 + \dots + \langle v, e_k \rangle e_k$$

① orthonormal \Rightarrow

$$\begin{cases} e_i^T e_j = 0, & i \neq j \\ \underbrace{e_i^T e_j}_{\|e_i\|} = 1, & i = j \end{cases}$$

③ any $v = \alpha_1 e_1 + \alpha_2 e_2 + \dots + \alpha_k e_k$

$$\alpha_i = \langle v, e_i \rangle$$

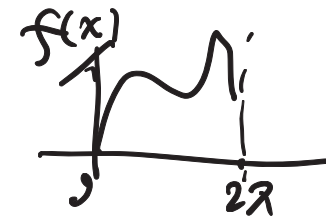
why? :

$$\langle v, e_i \rangle = \langle \alpha_1 e_1 + \dots + \alpha_k e_k, e_i \rangle$$

$$= \langle \alpha_i e_i, e_i \rangle = \alpha_i$$

② $\dim(V) = k$

Projection



- Fourier series: Consider a vector space of periodic functions:

$$V = \{ \text{integrable functions over } [0, 2\pi] \}$$

$f \in V \Rightarrow f$ integrable func on $[0, 2\pi]$

$$\int_0^{2\pi} \|f\|^2 dx < \infty$$

- Inner product: $\langle f, g \rangle = \int_0^{2\pi} f(x)g(x)dx$

- Basis: $B = \{ 1, \cos x, \sin(x), \cos(2x), \sin(2x), \dots \}$

$\phi_1(x) = 1$ $\phi_2(x)$ $\phi_3(x)$...
 " ϕ_i " are orthonormal:

$$\langle \phi_i, \phi_j \rangle = \begin{cases} 0, & \text{if } i \neq j \\ \pi, & \text{if } i = j \neq 1 \\ 2\pi, & \text{if } i = j = 1 \end{cases}$$

eg. $\int_0^{2\pi} \sin^2(x) dx = \pi$

- $f \in V$, then

$$f = \langle f, \frac{\phi_1}{\|\phi_1\|} \rangle \frac{\phi_1}{\|\phi_1\|} + \langle f, \frac{\phi_2}{\|\phi_2\|} \rangle \frac{\phi_2}{\|\phi_2\|} + \dots$$

Fourier expansion

$$f(x) = \underline{a_0} + \underline{a_1} \cos x + b_1 \sin x + \dots$$

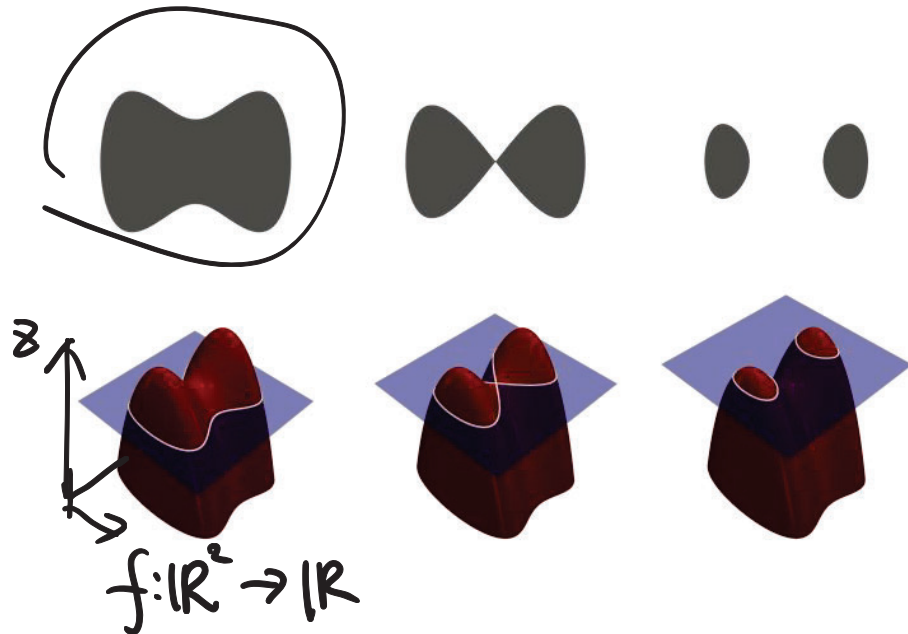
$$\left(\int_0^{2\pi} \frac{f(x) \cdot \cos x}{\sqrt{x}} dx \right) \frac{\cos x}{\sqrt{x}} = \left(\frac{1}{\pi} \int_0^{2\pi} f(x) \cos x dx \right) \cos x$$

a_1

Representation of Geometric Objects / sets

- Implicit representation via (sub)-level sets:

$$\{x \in \mathbb{R}^n : f(x) = 0\} \quad \text{or} \quad \{x \in \mathbb{R}^n : \underline{f(x) \leq 0}\}$$

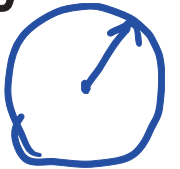


eg: $B = \{x \in \mathbb{R}^2 : \|x - x_c\|^2 \leq 1\}$

$$f(x) = \|x - x_c\|^2 - 1 \leq 0$$



$$C = \{x \in \mathbb{R}^2 : \|x - x_c\|^2 = 1\}$$



- Explicit representation: $\{x(\alpha) \in \mathbb{R}^n : \alpha \text{ satisfies certain conditions}\}$

$$B = \{x_c + \alpha : \alpha \in \mathbb{R}^2, \|\alpha\| \leq 1\}$$

$$C = \{(\cos \alpha, \sin \alpha) : \alpha \in [0, 2\pi)\}$$

connection with linear algebra:

$$f(x) \begin{cases} \text{linear} & f(x) = Ax + b \end{cases}$$

$$\left. \begin{array}{l} \\ \end{array} \right\} \text{or quadratic} \Rightarrow f(x) = x^T Q x$$

Some Simple Geometric Sets

- Line segment: Given $x_1 \neq x_2 \in R^n$: $\{x_2 + \alpha (x_1 - x_2) : \alpha \in [0,1]\}$
- Line (explicit): $\{x_2 + \alpha (x_1 - x_2) : \alpha \in R\}$
- Line: (implicit representation)
 - e.g. in R^2 : $\{x \in R^2 : a^T x = b\}$

Some Simple Geometric Sets

- Hyperplanes (Implicit): $\{x \in R^n: a^T x = b\}$
- Hyperplanes (Explicit): $\{x \in R^n: a^T x = b\} \Rightarrow \{x_0 + \sum_i \alpha_i v_i: \alpha_i \in R, i = 1, \dots, n - 1\}$
- Halfspaces: $\{x \in R^n: a^T x \leq b\}$

Some Simple Geometric Sets

- Convex set: A set S is called convex if

$$x_1, x_2 \in S \Rightarrow \alpha x_1 + (1 - \alpha)x_2 \in S$$

- **Convex combination** of $x_1, \dots, x_k \in R^n$

$$\{\alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_k x_k : \alpha_i \geq 0, \sum \alpha_i = 1\}$$

- Convex hull $\overline{\text{co}}(S)$: set of all convex combinations of points in S

Some Simple Geometric Sets

- **Cone:** A set S is called a cone if $x \in S \Rightarrow \lambda x \in S, \forall \lambda \geq 0$

- **Conic combination** of $x_1, \dots, x_k \in R^n$

$$\text{cone}(x_1, \dots, x_k) = \{\alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_k x_k : \alpha_i \geq 0\}$$

Some Simple Geometric Sets

- **(Convex) Polyhedron:** intersection of a finite number of half spaces

$$P = \{x : Ax \leq b\}$$

- **Polyhedral cone:** intersection of finitely many halfspaces that contain the origin:

$$P = \{x : Ax \leq 0\}$$

- **Polytope:** bounded polyhedron

Some Simple Geometric Sets

- Polyhedron (vertex representation):

$$P = \overline{\text{co}}(v_1, \dots, v_m) \oplus \text{cone}(r_1, \dots, r_q)$$

Some Simple Geometric Sets

- Euclidean balls: $B(x_c, r) = \{x \in R^n: \|x - x_c\|_2 \leq r\}$ or $B(x_c, r) = \{x_c + ru: u \in R^2, \|u\|_2 \leq 1\}$

- Ellipsoids: $E = \{x \in R^n: (x - x_c)^T P^{-1}(x - x_c) \leq 1\}$ or $E = \{x_c + Au: u \in R^2, \|u\|_2 \leq 1\}$

